CPE470/670.

**Project 2. Mobile Robot Path Planning using Artificial Potential Field**

**Total point: 100**

1. Design/Implement an Artificial Potential Controller to allow a mobile robot to follow/track a virtual moving target (See Project 2-Instruction, pages 2-4)
2. Write Matlab or C/Cpp code (or other languages you prefer) to implement your designed potential controller.
3. Write a report of the project to cover the following items:
   1. **(50 points)** Noise free environment (robot is assumed to localize itself accurately without noise, and be able to sense target position accurately):
      * Plan the target to move in a linear/line trajectory and plot the tracking results: (i) trajectories of the target and robot, (ii) tracking error between the target and robot, (iii) robot’s heading; and (iv) robot’s velocity. **(25 points).**
      * Plan the target to move in the sine wave trajectory and plot the tracking results: (i) trajectories of the target and robot, (ii) tracking error between the target and robot, (iii) robot’s heading, and (iv) robot’s velocity. **(25 points).**
   2. **(50 points)** Noisy environment (robot is assumed to be able to sense the target, but with noise ). You can use Gaussian noise model (randn function), a similar noise function in the project 1:
      * Add noise to the target position. Then, plan the target to move in a linear/line trajectory and plot the tracking results: (i) trajectories of the target and robot, (ii) tracking error between the target and robot, (iii) robot’s heading, and (iv) robot’s velocity. **(25 points).**
      * Add noise to the target position. Then, plan the target to move in the sine wave trajectory and plot the tracking results: (i) trajectories of the target and robot, (ii) tracking error between the target and robot, (iii) robot’s heading, and (iv) robot’s velocity. **(25 points).**
   3. Put all the source code/software in the Appendix with instruction of running the code
4. **Project Deadline: March 24th, 2022**

* **Submit the project report with source code into Canvas.**
* **The code must be written by you. Do NOT use or copy code from online or other sources. Plagiarism will be 0 grade penalty.**